On delta-convex functions

Miroslav Bačák & Jonathan M. Borwein

CARMA University of Newcastle http://carma.newcastle.edu.au/jon/dctalk.pdf

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Australian and New Zealand Industrial and Applied Mathematics



Abstract

Advances over the past fifteen years have lead to a rich current theory of difference convex functions. I shall describe the state of our knowledge and highlight some open questions.

• A fine survey of the subject two decades ago is:



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Outline

Basic structure of DC functions
 Examples of DC functions

 Polynomials in several variables
 Variational analysis
 Nash equilibria
 Eigenvalues
 Further operator theory

 Finer structure of DC functions

 Differentiability
 Eigenvalues
 Eigenvalues
 Eigenvalues
 Eigenvalues
 Eigenvalues
 Eigenvalues

Composition of DC mappings Toland duality

4 Negative results

Composition of DC mappings Finite vs infinite dimensions Differentiability

5 Distance functions

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Definition of DC functions

Definition (DC functions)

Let X be a normed linear space. A function $f : X \to \mathbb{R}$ is delta-convex (or DC) (on an open Ω) if there exist convex continuous functions f_1, f_2 on X such that $f = f_1 - f_2$ (on Ω)

• Can typically assume $f_1, f_2 \ge 0$ by adding affine minorants.

Conjecture

Delta-convex functions first appeared in the paper:

• H. Busemann and W. Feller, "Krümmungseigenschaften Konvexer Flächen." Acta Math. **66** (1936), 1–47.

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DC mappings between Euclidean spaces

Definition (DC mappings between Euclidean spaces)

A mapping $F = (F_1, \ldots, F_m) : \mathbb{R}^n \to \mathbb{R}^m$ is *DC* if all the components F_1, \ldots, F_m are DC functions.

 f: [a, b] → ℝ is DC if and only if f is absolutely continuous (AC) and f' has bounded variation (BV) – precisely a difference of two nondecreasing functions.

A fundamental and still instructive paper is:

- P. Hartman, "On functions representable as a difference of convex functions." *Pacific J. Math.* **9** (1959), 707–713.
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DC mappings in infinite dimensions

Definition (DC mappings with infinite dimensional range)

Let X, Y be normed linear spaces. We say that $F : X \to Y$ is DC (on an open Ω) if there exists a continuous convex *control function* $f : X \to \mathbb{R}$ such that

 $y^* \circ F + f$

is convex (on Ω) for all $y^* \in Y^*$, with $||y^*|| = 1$.

This is a clever scalarization definition — even for real valued functions — by

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Order DC mappings

Recall that $F: \Omega \subset X \mapsto Y$ is S-convex (order-convex) when

 $\mathrm{Epi}_S(F) := \{(x,y): F(x) \in y + S, x \in \Omega\}$

is convex and $S \subset Y$ us a convex cone.

• If $G = F_1 - F_2$ with F_1, F_2 both S-convex, we say G is S-DC or order-DC.

Theorem (Order Convexity)

Suppose S is a convex cone whose dual S^+ has nonempty interior.

- Then every S-DC operator is DC. (Can vary the S.)
- In particular, \mathbb{R}^N_+ -DC and DC coincide in \mathbb{R}^N .

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Structural properties

Theorem (Structure)

The real-valued DC functions on an open set form a subspace of locally Lipschitz functions and:

a vector space;

2 an algebra (closed under multiplication);

3 a lattice (closed under finite maxima/minima).

Indeed, much more is true:

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Mixing properties — 'convex under switching'

Theorem (Mixing, Veselý-Zajíček, 2001)

Let g_1, g_2, \ldots, g_n be DC on Ω . Any continuous selection σ with

 $\sigma(x) \in \{g_1(x), g_2(x), \dots, g_n(x)\}$

for all $x \in \Omega$ is also a DC function. In particular, each piecewise linear and continuous function is DC.

A nice (partial) converse is:

Theorem (Absoluteness)

Let f be continuous, real-valued. Then |f| is DC if and only if f is.

• This converse fails for ||f||.

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On delta-convex functions

Polynomials in several variables Variational analysis Nash equilibria Eigenvalues Further operator theory

Examples of DC functions

We now present various examples of DC functions arising naturally:

- Polynomials in several variables
- Variational analysis
- Non-cooperative game theory
- Spectral theory
- Operator theory

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Polynomials in several variables Variational analysis Nash equilibria Eigenvalues Further operator theory

Polynomials in several variables

Theorem (Polynomials)

Polynomials on \mathbb{R}^N are DC: each polynomial p can be decomposed as p = q - r where r, q are nonnegative convex functions.

- Hence, DC functions are dense uniformly in $C(\Omega)$ for compact Ω there are too many of them.
- Easy induction: $x^{2n-1} = (x^+)^{2n-1} (x^-)^{2n-1}$ and x^{2n} are DC in an algebra (Structure Thm), as positive convex squares are convex and: $\pm 2fg = (|f| + |g|)^2 |f|^2 |g|^2$.

Conjecture

There is a concise explicit determinantal decomposition in \mathbb{R}^N .

• I found one 35 years ago but have lost it!

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Variational analysis

Definition

A function $f: X \to \mathbb{R}$ is *paraconvex* if there is $\lambda \ge 0$ such that $f + \frac{\lambda}{2} \| \cdot \|^2$ is continuous and convex; -f is *paraconcave*.

Example

Clearly, paraconvex and paraconcave functions are 'very' DC

• On Hilbert space, locally paraconvex = lower- C^2 .



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On delta-convex functions

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Non-cooperative game theory

n-player games

Player i has:

- pure strategies $(\pi_{i\alpha})_{\alpha}$
- mixed strategies $S_i = \text{convex combination}$
- pay-off function $p_i(\pi_{1\alpha_1}, \ldots, \pi_{i\alpha_i}, \ldots, \pi_{n\alpha_n})$

Definition (Equilibrium)

$$p_i(s) = \max_{t_i \in S_i} p_i(s_1, \dots, s_{i-1}, t_i, s_{i+1}, \dots, s_n).$$



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Definition (Equilibrium)

$$p_i(s) = \max_{t_i \in S_i} p_i(s_1, \dots, s_{i-1}, t_i, s_{i+1}, \dots, s_n).$$



Polynomials in several variables Nash equilibria Eigenvalues Further operator theory

Theorem (Nash, 1951)

Assuming convexity of all $t_i \mapsto p_i(s_1, \ldots, s_{i-1}, t_i, s_{i+1}, \ldots, s_n)$, every Nash game admits an equilibrium point.

$$s_i' := \frac{s_i + \sum_{\alpha} \varphi_{i\alpha} \pi_{i\alpha}}{1 + \sum_{\alpha} \varphi_{i\alpha} \pi_{i\alpha}}.$$

• T is DC as a DC ratio (not so useful; only in Euclidean space). Convexity insures T is a self-map.

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Sketch of Nash's proof.

Denote $p_{i\alpha}(s) := p_i(s, \pi_{i\alpha})$, and define DC functions $\varphi_{i\alpha}(s) := \max \{0, p_{i\alpha}(s) - p_{\alpha}(s)\} \quad i = 1, \dots, n.$ Define $T: s \mapsto s'$ componentwise by

$$s_i' := \frac{s_i + \sum_{\alpha} \varphi_{i\alpha} \pi_{i\alpha}}{1 + \sum_{\alpha} \varphi_{i\alpha} \pi_{i\alpha}}$$

Equilibria are fixed points of T, which exist (Brouwer).

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Spectral theory in finite dimensions

Denote by S_N the set of real symmetric N by N matrices.

Theorem (Lewis, 1995)

The k^{th} -largest eigenvalue function

 $\lambda_k: A \to \lambda_k(A)$

is DC on the space of symmetric matrices S_N . Indeed,

 $\lambda_k = \sigma_k - \sigma_{k-1}$

where σ_k , the sum of the k largest eigenvalues, is convex for all k.

• Try proving *directly* that λ_k is locally Lipschitz.

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Polynomials in several variables Variational analysis Nash equilibria **Eigenvalues** Further operator theory

The 3×3 case

There are three eigenvalues: $\lambda_1, \lambda_2, \lambda_3$, and $\operatorname{Trace} = \lambda_1 + \lambda_2 + \lambda_3$. Now $\lambda_1(A) = \lambda_{MAX}(A) = \max_{\|x\|=1} \langle Ax, x \rangle$ is convex (Rayleigh-Ritz) and $\lambda_3 = \lambda_{MIN} = -\lambda_{MAX}(-\cdot)$ is concave (R-R). Then

$$\lambda_2 = \operatorname{Trace} -\lambda_1 - \lambda_3$$

is a DC decomposition.



One-D and two-D cross-sections of λ_2

Basic structure of DC functions Examples of DC functions Finer structure of DC functions Negative results Distance functions Finer structure of DC functions Negative results Distance functions Further operator theory

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One-D and two-D cross-sections of λ_2

Polynomials in several variables Variational analysis Nash equilibria Eigenvalues Further operator theory

Spectral theory in infinite dimensions

Denote by \mathcal{B}_{sa} the self-adjoint bounded linear operators on $\ell^2_{\mathbb{C}}$.

Definition (Schatten classes)

 $A \in \mathcal{B}_{sa}$ belongs to the 0-Schatten class if it is compact, and belongs to the *p*-Schatten class, \mathcal{B}_p , for $p \in [1, +\infty)$, if

 $||A||_p := (\operatorname{Trace}(|A|^p))^{1/p} < \infty,$

where $|A| := (A^*A)^{1/2}$.

 Then B₂ is the *Hilbert-Schmidt operators* — a Hilbert space — and B₁ is the *trace class* or *nuclear operators*.

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Consider positive operators such that $\langle Ax, x \rangle \geq 0$ for all $x \in \ell^2_{\mathbb{C}}$.

Theorem (B-Z, 2005)

For $p \in \{0\} \cup [1, +\infty)$ the k^{th} -largest eigenvalue function $\lambda_k : A \to \lambda_k(A)$ is DC on the set of positive operators of *p*-Schatten class.

Example

Despite not living on the nuclear operators — as induced by $\sum_i t_i - \log(1 + t_i)$ — we have :

 $A \mapsto \operatorname{Trace}(A) - \log \det(I + A)$

is a convex barrier on \mathcal{B}_2 , for $\{A \colon I + A \ge 0\}$.

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Further operator theory

Let X be a Banach space. Each symmetric bounded linear operator $T: X \to X^*$ generates a quadratic form on X by $x \mapsto \langle Tx, x \rangle$.

- When is a quadratic form DC?
- X is a UMD space if this holds for all symmetric T?

Theorem (Kalton-Konyagin-Veselý, 2008)

The quadratic form

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Further operator theory

- All UMD spaces are super-reflexive;
- W_p and \mathcal{B}_p and so L_p is UMD for 1 . Hence:

Proposition

Let T be a symmetric bounded linear operator on a Hilbert space. Then the function $x \mapsto \langle Tx, x \rangle$ is DC on X.

- Alternative proof: Clearly $\langle T\cdot,\cdot\rangle$ is $C^{1,1}$, which in Hilbert spaces implies DC.
- A stronger result: $\langle T \cdot, \cdot \rangle$ is a difference of two nonnegative quadratic forms (necessarily convex): $T = \frac{|T|+T}{2} \frac{|T|-T}{2}$.

- "X is type (DCQ)" \Leftarrow type $p \ge 2$; $\ell^p(p < 2)$ is not (DCQ).

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Differentiability Composition of DC mappings Toland duality

Finer structure of DC functions



JMB and MB

M. Bačák, J. Borwein On delta-convex functions

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Differentiability Composition of DC mappings Toland duality

Differentiability properties

• The Clarke subdifferential on \mathbb{R}^N .

Theorem (Euclidean properties)

Let $f : \mathbb{R}^n \to \mathbb{R}$ be DC with a decomposition $f = f_1 - f_2$. Then,

- **2** $\partial_{\mathsf{C}} f$ reduces to ∇f a.e. on \mathbb{R}^n ; so a.e. strictly differentiable;
- **(3)** f has a second-order Taylor expansion a.e. on \mathbb{R}^n .

Proof of 1.

 $(f-g)^{o}(x;h) \leq (f)^{o}(x;h) + (-g)^{o}(x;h) = (f)^{'}(x;h) + (-g)^{'}(x;h).$

(Find a minimal decomposition with equality?)

• $\partial_{\mathsf{C}} f(x)$ need not be singleton when f is differentiable at $x \in \mathbb{R}^n$ i.e., DC need not be *regular*

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(Find a minimal decomposition with equality?)

• $\partial_{\mathsf{C}} f(x)$ need not be singleton when f is differentiable at $x \in \mathbb{R}^n$ i.e., DC need not be *regular*

Differentiability Composition of DC mappings Toland duality

Differentiability properties

• The Clarke subdifferential on \mathbb{R}^N .

Theorem (Euclidean properties)

Let $f : \mathbb{R}^n \to \mathbb{R}$ be DC with a decomposition $f = f_1 - f_2$. Then,

- $\textbf{0} \ \partial_{\mathsf{C}} f(x) \subset \partial_{\mathsf{C}} f_1(x) \partial_{\mathsf{C}} f_2(x) \text{ for all } x \in \mathbb{R}^n;$
- **2** $\partial_{\mathsf{C}} f$ reduces to ∇f a.e. on \mathbb{R}^n ; so a.e. strictly differentiable;
- **(3)** f has a second-order Taylor expansion a.e. on \mathbb{R}^n .

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Differentiability Composition of DC mappings Toland duality

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Theorem (Banach properties, Veselý-Zajíček, 2001)

Let X be a Banach space and $A \subset X$ an open convex subset. Suppose $f : A \to \mathbb{R}$ is locally DC.

- All one-sided directional derivatives of f exist on A.
- If X is Asplund, then f is strictly Fréchet differentiable everywhere on A excepting a set of the first category.
- If X is weak Asplund, then f is strictly Gâteaux differentiable everywhere on A excepting a set of the first category.

Differentiability Composition of DC mappings Toland duality

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Differentiability Composition of DC mappings Toland duality

Differentiability properties

Differentiability of the control function.

Proposition (Veselý-Zajíček, 2001)

Let X be a normed linear space and $A \subset X$ open and convex. Suppose $f : A \to \mathbb{R}$ is DC on A with a control function \tilde{f} .

- If \tilde{f} is Fréchet differentiable at $x \in A$, then f is strictly Fréchet differentiable at x.
- 2 If \tilde{f} is Gâteaux differentiable at $x \in A$, then f is Gâteaux differentiable at x.

Recall: f is DC if and only if there exists a continuous convex function \tilde{f} such that both $\pm f + \tilde{f}$ are convex:

 $\widetilde{f} = control \ function$

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Differentiability Composition of DC mappings Toland duality

Composition of DC mappings

Theorem (Hartman, 1959)

Let $A \subset \mathbb{R}^m$ be convex and either open or closed. Let $B \subset \mathbb{R}^n$ be convex and open. If $F : A \to B$ and $g : B \to \mathbb{R}$ are DC, then $g \circ F$ is a locally DC function on A.

Theorem (Veselý, Zajíček, 1987, 2009)

Let X, Y be normed linear spaces, $A \subset X$ a convex set, and $B \subset Y$ open convex. If $F : A \to B$ and $g : B \to \mathbb{R}$ are locally DC, then $g \circ F$ is locally DC on A.

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Differentiability Composition of DC mappings Toland duality

Toland duality, 1978

For a function $f:X\to (-\infty,\infty]$ on a Banach space X define its conjugate function by

$$f^*(x^*) := \sup_{x \in X} \{ \langle x^*, x \rangle - f(x) \} \qquad x^* \in X^*.$$

Theorem (Ellaia and Hiriart-Urruty, 1986)

Let X be a Banach space, $h: X \to \mathbb{R}$ be convex continuous, and $g: X \to (-\infty, \infty]$ any function. Then for each $x^* \in \text{dom } g^*$,

$$(g-h)^*(x^*) = \sup_{y^* \in \mathrm{dom}\,h^*} \left\{ g^*(x^*+y^*) - h^*(y^*) \right\}$$

• This statement — or various critical point consequences — is now called *Toland duality*.

Toland is the new Director of the Newton Institute

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Differentiability Composition of DC mappings Toland duality

Toland duality

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Let X be a Banach space, $h: X \to \mathbb{R}$ be convex continuous, and $g: X \to (-\infty, \infty]$ any function. Then

$$\inf_{x \in X} g(x) - h(x) = \inf_{x^* \in \mathrm{dom} \, h^*} h^*(x^*) - g^*(x^*). \tag{1}$$

Corollary

If we assume both g, h are continuous convex, and so g - h is DC on X, we arrive at (1) along with

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Negative results



"Now that we can tell time, I'd like to suggest that we begin imposing deadlines."

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Counterexamples to composition

• A composition of DC functions that is not DC:

Example (Hartman, 1959)

The composition of DC functions need not be DC even in $\ensuremath{\mathbb{R}}.$ Consider

$$f:(0,1) \to [0,1): x \mapsto |x-1/2|,$$

and

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g: [\mathbf{0}, 1) \to \mathbb{R}: y \mapsto 1 - \sqrt{y}.
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Then $g \circ f$ is not DC at 1/2.

• Note: $0 \notin int[0,1)$.

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Counterexamples to composition, I



Figure: $g \circ f = 1 - \sqrt{|\cdot - 1/2|}$ is not DC around 1/2.

- One-sided derivatives of g
 of infinite at 1/2 (DC have finite limits).
- Failure of openness constraint qualification (CQ) is to blame.

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Composition of DC mappings Finite vs infinite dimensions Differentiability

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Counter-examples to composition, II

What follows is a very general method of constructing composition counter-examples:

Theorem (Veselý-Zajíček, 2009)

Let X, Y be infinite-dimensional normed linear spaces. Let $A \subset X$ and $B \subset Y$ be convex with A open. Suppose $g: B \to \mathbb{R}$ is unbounded on some bounded subset of B. Then there exists a DC mapping $F: A \to B$ such that $g \circ F$ is not DC on A.

• We give a fairly concrete realization of F and g in our paper.

Composition of DC mappings Finite vs infinite dimensions Differentiability

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Finite vs infinite dimensions

Theorem (Veselý, Zajíček, 2009)

Let X be a normed linear space and $A \subset X$ open convex set. Then the following are equivalent.

- **1** X is infinite-dimensional.
- 2 There is a positive DC function f on A such that 1/f is not DC on A.
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Composition of DC mappings Finite vs infinite dimensions Differentiability

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Finite vs infinite dimensions and reflexivity

• Reciprocals of convex functions yield a striking variant.

Theorem (Holický et al, 2007)

X is reflexive (resp. finite dim.) if and only if every positive continuous convex (resp. DC) function on X has 1/f DC.

• Another striking limiting example is:

Theorem (Kopecká-Malý, 1990)

There exists a function on ℓ_2 which is DC on each bounded convex subset of ℓ_2 but is not DC on ℓ_2 .

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Composition of DC mappings Finite vs infinite dimensions Differentiability

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Composition of DC mappings Finite vs infinite dimensions Differentiability

Counterexamples to differentiability theorems

Theorem (Kopecká, Malý, 1990)

There exists a DC function on \mathbb{R}^2 which is strictly Fréchet differentiable at the origin but which does not admit a control function that is Fréchet differentiable at the origin.

Theorem (Pavlica, 2005)

There exists a DC function on \mathbb{R}^2 which belongs to the class \mathcal{C}^1 but does not admit a control function that is Fréchet differentiable at the origin.

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Distance functions



THE COLLATZ CONJECTURE STATES THAT IF YOU PICK. A NUMBER, AND IF ITS EVEN DIVIDE IT BY TWO AND IF IT'S ODD MULTIPLY IT BY THREE AND ADD ONE, AND YOU REPEAT THIS PROCEDURE LONG ENOUGH, EVENTUALLY YOUR FRIENDS WILL STOP CALLING TO SEE IF YOU WANT TO HANG OUT.

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Distance functions: positive results

Observation (Asplund, 1969)

 d_C^2 is paraconcave and so DC for $C \subset X$ closed in Hilbert space:

$$d_C^2(x) = -\sup_{c \in C} -\|x - c\|^2 = \|x\|^2 - [\sup_{c \in C} 2\langle x, c \rangle - \|c\|^2].$$

• The smooth variational principle produces:

Theorem (Borwein 1991, Borwein-Zhu, 2005)

For $C \subset X$ closed in Hilbert space, d_C is locally DC on $X \setminus C$ while $\partial_{\mathsf{C}} d_C$ is a minimal CUSCO on X.

• Asplund's result and the B-Z theorem allows proximal analysis on Hilbert space to be done *without* Rademacher's theorem.

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Distance functions: negative results

Example (Borwein-Moors, 1997)

There is a closed set $C \subset \mathbb{R}^2$ with d_C not (locally) DC on \mathbb{R}^2 . **Proof**: Let $C := C_1 \times C_1 \subset \mathbb{R}^2$ for $C_1 \subset [0,1]$ be a Cantor set of positive measure.

 d_C is not strictly differentiable anywhere on $\mathrm{bd}(C) = C$.

So d_C is not locally DC; as DC functions are a.e. strictly Fréchet.

- In particular, the operation $\sqrt{\cdot}$ does not preserve DC.
- d_C is a very rich tool for building counter-examples.

Question

If the norm on a Banach space X is sufficiently nice, is d_C^2 DC locally for all closed sets C on X (d_C on $X \setminus C$)?

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References — and many thanks to Regina and Yalcin

This talk was based on the paper:

- M. Bačák¹ and J.M. Borwein, "On difference convexity of locally Lipschitz functions." *Optimization*, 2011. (For Alfredo lusem at 60.)
- Preprint available at: http: //carma.newcastle.edu.au/jon/dc-functions.pdf

Additional information is to be found in:

- J.M. Borwein and J. Vanderwerff, *Convex Functions: Constructions, Characterizations and Counterexamples*, CUP, 2010.
- Website:

http://carma.newcastle.edu.au/ConvexFunctions/

¹Now at Max Planck Institute, Leipzig