

# Introduction to CAT(0) spaces

**Miroslav Bačák**

CARMA, University of Newcastle

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- 1 Geodesics and angles
- 2 CAT(0) spaces
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# Geodesics

Let  $(X, d)$  be a metric space. A *geodesic* joining  $x \in X$  to  $y \in X$  is a mapping  $\gamma : [0, d(x, y)] \rightarrow X$  such that

- $\gamma(0) = x$ ,
- $\gamma(d(x, y)) = y$ ,
- $d(\gamma(t_1), \gamma(t_2)) = |t_1 - t_2|$  for any  $t_1, t_2 \in [0, d(x, y)]$ .

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## Comparison triangle

Let  $(X, d)$  be a geodesic metric space. A *geodesic triangle* consists of three points  $p, q, r \in X$  and three geodesics  $[p, q], [q, r], [r, p]$ . Denote  $\Delta([p, q], [q, r], [r, p])$ .

For such a triangle, there is a *comparison triangle*  $\bar{\Delta}(\bar{p}, \bar{q}, \bar{r}) \subset \mathbb{R}^2$  :

- $d(p, q) = d(\bar{p}, \bar{q})$
- $d(q, r) = d(\bar{q}, \bar{r})$
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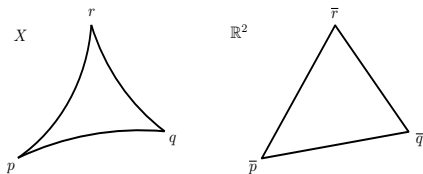
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# Length space

Let  $(X, d)$  be a metric space. A *curve* is a continuous mapping from a compact interval to  $X$ .

The *length* of a curve  $\gamma : [a, b] \rightarrow X$  is

$$\ell(\gamma) = \sup_{\mathcal{P}} \sum_{i=1}^{n-1} d(\gamma(t_i), \gamma(t_{i+1})),$$

where  $\mathcal{P}$  stands for the set of partitions of  $[a, b]$ .

## Definition

$(X, d)$  is a *length space* if for any  $x, y \in X$  we have

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# Angles

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Let  $X$  be a geodesic space. We define the *Alexandrov angle* between two geodesics  $\gamma_1 : [0, t_1] \rightarrow X$  and  $\gamma_2 : [0, t_2] \rightarrow X$  with  $\gamma_1(0) = \gamma_2(0)$  by

$$\alpha(\gamma_1, \gamma_2) = \limsup_{t_1, t_2 \rightarrow 0} \sphericalangle(\gamma_1(t_1), \gamma_1(0), \gamma_2(t_2)).$$

So, the angle is a number from  $[0, \pi]$ . In CAT(0) spaces:

- one can take  $\lim$  in place of  $\limsup$ ,
- $\alpha(\gamma_1, \gamma_2) = \lim_{t \rightarrow 0} 2 \arcsin \frac{1}{2t} d(\gamma_1(t), \gamma_2(t))$ ,
- for a fixed  $p \in X$  the function  $\alpha(\cdot, p, \cdot)$  is continuous on  $X^2$ ,
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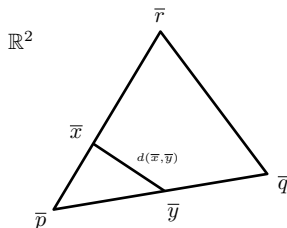
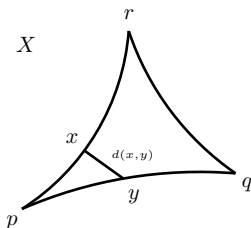
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- ① Geodesics and angles
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# Definition of CAT(0) space

## Definition (CAT(0) space)

Let  $(X, d)$  be a geodesic space. It is a CAT(0) space if for any geodesic triangle  $\Delta \subset X$  and  $x, y \in \Delta$  we have  $d(x, y) \leq d(\bar{x}, \bar{y})$ , where  $\bar{x}, \bar{y} \in \bar{\Delta}$ .



# Basic properties

Let  $X$  be a CAT(0) space. Then we have

- 1 For each  $x, y \in X$  there is a unique geodesic connecting  $x, y$ .
- 2 Geodesics vary continuously with their end points.
- 3  $X$  is Ptolemaic, i.e. the Ptolemy inequality holds:

$$d(x, y)d(u, v) \leq d(x, u)d(y, v) + d(x, v)d(y, u).$$

- 4  $X$  is Busemann convex, i.e. for geodesics  $\gamma_1, \gamma_2 : [a, b] \rightarrow X$  the function  $t \mapsto d(\gamma_1(t), \gamma_2(t))$ ,  $t \in [a, b]$  is convex.

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# Equivalent conditions

## Proposition

*Let  $X$  be a complete metric space. Then  $X$  is a length space if and only if for any  $x, y \in X$  and  $\delta > 0$  there is  $m \in X$  such that*

$$\max \{d(x, m), d(y, m)\} \leq \frac{1}{2}d(x, y) + \delta.$$

## Proposition (Menger)

*Let  $X$  be a complete metric space. Then  $X$  is geodesic if and only if for any  $x, y \in X$  there exists  $m \in X$  such that*

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Let  $X$  be a complete metric space. The following conditions are equivalent.

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- ② For any  $a, b \in X$  and  $\delta > 0$  there is  $m \in X$  such that  $\max \{d(a, m), d(b, m)\} \leq \frac{1}{2}d(a, b) + \delta$ , and for any  $x_1, x_2, y_1, y_2 \in X$  there exist  $\bar{x}_1, \bar{x}_2, \bar{y}_1, \bar{y}_2 \in \mathbb{R}^2$  such that  $d(x_i, y_j) = d(\bar{x}_i, \bar{y}_j)$  for  $i, j \in \{1, 2\}$ , and  $d(x_1, x_2) \leq d(\bar{x}_1, \bar{x}_2)$  and  $d(y_1, y_2) \leq d(\bar{y}_1, \bar{y}_2)$ .

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- ③ For every triangle  $\Delta ([p, q], [q, r], [r, p]) \subset X$  and every  $x \in [p, q], y \in [p, r]$  with  $x \neq p$  and  $y \neq p$ , we have

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# Equivalent conditions

## Proposition (...continued)

- ④ *The angle between the sides of any geodesic triangle in  $X$  with distinct vertices is no greater than the angle between the corresponding sides of its comparison triangle.*
- ⑤ *For every triangle  $\Delta([p, q], [q, r], [r, p]) \subset X$  with  $p \neq q$  and  $p \neq r$ , if  $\Delta([a, b], [b, c], [c, a]) \subset \mathbb{R}^2$  is a triangle with  $d(p, q) = d(a, b)$ ,  $d(p, r) = d(a, c)$  and  $\angle(b, a, c) = \alpha(q, p, r)$ , then  $d(q, r) \geq d(b, c)$ .*
- ⑥ *For any  $x, y, z \in X$  and  $m \in X$  with  $2d(y, m) = 2d(m, z) = d(y, z)$  we have*

$$d(x, y)^2 + d(x, z)^2 \geq 2d(x, m)^2 + \frac{1}{2}d(y, z)^2.$$



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*A geodesic space  $X$  is CAT(0) if and only if it is Ptolemaic and Busemann convex.*

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Proposition (Berg, Nikolaev, (pf: Sato))

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$$d(x, u)^2 + d(y, v)^2 \leq d(x, y)^2 + d(y, u)^2 + d(u, v)^2 + d(v, x)^2$$

Remark

- Answers a question of Gromov
- Roundness 2 (Enfo)
- The inequality holds for instance for the metric space  $(Y, \sigma^{1/2})$  where  $(Y, \sigma)$  is an arbitrary metric space.

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- 1 Geodesics and angles
- 2 CAT(0) spaces
- 3 Examples**
- 4 Metric projections
- 5 Open problems

# Examples

- 1 Hilbert spaces – the only Banach spaces which are CAT(0)
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- ① Geodesics and angles
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# Projections

## Definition

Let  $X$  be a uniquely geodesic space. A set  $M \subset X$  is *convex* if, given  $x, y \in M$ , we have  $[x, y] \subset M$ .

Let  $(X, d)$  be a complete CAT(0) space and  $C \subset X$  be a convex closed set. Define the *distance function* by

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Let  $C \subset X$  be closed and convex. Then

- 1 for every  $x \in X$ , there exists a unique point  $P_C(x) \in C$  such that  $d(x, P_C(x)) = d(x, C)$ .
- 2 For any  $y \in [x, P_C(x)]$  we have  $P_C(y) = P_C(x)$ .
- 3 For any  $x \in X \setminus C$  and  $y \in C \setminus \{P_C(x)\}$  we have

$$\alpha(x, P_C(x), y) \geq \frac{\pi}{2}.$$

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## Nice projections on geodesics

### Definition

We shall say that  $X$  has the *property (N)* if, given a geodesic  $\gamma$  and  $x, y \in X$ , we have that  $P_\gamma(m)$  lies on the geodesic from  $P_\gamma(x)$  to  $P_\gamma(y)$ , for any  $m \in [x, y]$ .

Do all complete CAT(0) spaces have the property (N)?



# A non-empty intersection

...on the blackboard

# Suggestions for our next talks

- Examples (hyperbolic spaces, manifolds, buildings, . . . )
- Connections to Banach space geometry
- Topologies on  $CAT(0)$  spaces
- Alternating projections
- Fixed point theory
- Applications (phylogenetic trees)

# Metric projections onto convex sets

**Miroslav Bačák**

CARMA, University of Newcastle

30 March 2010

# Contents of the talk

## 1 Warm-up

Cosine rule

Inversion in metric spaces

## 2 Metric projections

Definitions

Main theorem(s)

Weak convergence

## 3 Final remarks

# Cosine rule

Recall:

## Proposition

Let  $X$  be a geodesic space. TFAE

- 1  $X$  is CAT(0).
- 2 For every triangle  $\Delta([p, q], [q, r], [r, p]) \subset X$  with  $p \neq q$  and  $p \neq r$ , if  $\Delta([a, b], [b, c], [c, a]) \subset \mathbb{R}^2$  is a triangle with  $d(p, q) = d(a, b)$ ,  $d(p, r) = d(a, c)$  and  $\angle(b, a, c) = \alpha(q, p, r)$ , then  $d(q, r) \geq d(b, c)$ .

Equivalently:

$$w^2 \geq u^2 + v^2 - 2uv \cos \gamma.$$

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# Ptolemy inequality

A metric space is Ptolemaic if the Ptolemy inequality holds:

$$d(x, y)d(u, v) \leq d(x, u)d(y, v) + d(x, v)d(y, u).$$

A geodesic space is Busemann convex if for any  $\gamma_1, \gamma_2 : [a, b] \rightarrow X$  the function  $t \mapsto d(\gamma_1(t), \gamma_2(t))$ ,  $t \in [a, b]$  is convex.

## Proposition

*A geodesic space  $X$  is CAT(0) if and only if it is Ptolemaic and Busemann convex.*

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# Inversion about sphere

Let  $(X, d)$  be a metric space. Fix  $p \in X$ . Define

$$i_p(x, y) = \frac{d(x, y)}{d(x, p)d(p, y)} \quad x, y \in X \setminus \{p\}.$$

It is not a metric in general.

## Proposition

*Let  $X$  be Ptolemaic, then  $i_p$  is a metric on  $X \setminus \{p\}$ .*

Inversion: nearest point mapping  $\iff$  farthest point mapping.

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For any  $x \in X$  denote its *projection* onto  $C$  by

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If the set  $P_C(x)$  is a singleton, for every  $x \in X$ , we say  $C$  is Čebyšev.

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# Convexity of $d_C$

## Proposition

Let  $X$  be a CAT(0) space and  $C \subset X$  convex complete. Then:

- 1  $d_C$  is convex.
- 2 For all  $x, y$  we have  $|d_C(x) - d_C(y)| \leq d(x, y)$ .

## Proof.

- 1 By convexity of  $d$ .
- 2  $d_C(x) \leq d(x, P_C(y)) \leq d(x, y) + d(y, P_C(y)) = d(x, y) + d_C(y)$ .



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## Proposition

Let  $X$  be a CAT(0) space and  $C \subset X$  a Čebyšev set. If  $P_C$  is nonexpansive, then  $C$  is convex.

## Proof.

By contradiction, suppose there are  $x, y \in C$  such that the point  $m \in [x, y]$  with  $d(x, m) = d(m, y)$  is not in  $C$ . If both  $d(x, P_C(m))$  and  $d(y, P_C(m))$  were less than or equal to  $d(x, m)$ , we would have another geodesic from  $x$  to  $y$  distinct from  $[x, y]$ , namely  $[x, P_C(m)] \cup [P_C(m), y]$ . Without loss of generality, let  $d(x, P_C(m)) > d(x, m)$ . But this yields a contradiction, since  $P_C(x) = x$  and  $P_C$  is nonexpansive. □

# Weak convergence

Suppose  $(x_n) \subset X$  is a bounded sequence and define its *asymptotic radius* about a given point  $x \in X$  as

$$r(x_n, x) = \limsup_{n \rightarrow \infty} d(x_n, x),$$

and the *asymptotic radius* as

$$r(x_n) = \inf_{x \in X} r(x_n, x).$$

Further, we say that a point  $x \in X$  is the *asymptotic center* of  $(x_n)$  if

$$r(x_n, x) = r(x_n).$$

Recall that the asymptotic center of  $(x_n)$  exists and is unique, if  $X$  is a complete CAT(0) space.

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# Weak convergence

## Definition

We shall say that  $(x_n) \subset X$  *weakly converges* to a point  $x \in X$  if  $x$  is the asymptotic center of each subsequence of  $(x_n)$ . We use the notation  $x_n \xrightarrow{w} x$ .

Clearly, if  $x_n \rightarrow x$ , then  $x_n \xrightarrow{w} x$ .

## Lemma

Let  $X$  be a  $CAT(0)$  space and  $(x_n) \subset X$  a bounded sequence. Then there is a subsequence  $(x_{n_k})$  of  $(x_n)$  and a point  $x \in X$  such that  $x_n \xrightarrow{w} x$ .

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Let  $X$  be a  $CAT(0)$  space and  $C \subset X$  closed convex. If  $(x_n) \subset C$  and  $x_n \xrightarrow{w} x \in X$ , then  $x \in C$ .

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Let  $X$  be a  $CAT(0)$  space and  $C \subset X$  closed convex. The distance function  $d_C$  is weakly (sequentially) lsc, i.e., for any  $x_n \xrightarrow{w} x$ ,

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# An alternative proof

## Theorem (Projection theorem revisited)

Let  $X$  be a  $CAT(0)$  space and  $C \subset X$  complete convex. Then, for any  $x \in X$ , there exists a point  $c \in C$  such that  $d_C(x) = d(c, x)$ .

### Proof.

Let  $x \in X$ . There exists  $(c_n) \subset C$  such that  $d(c_n, x) \rightarrow d_C(x)$ . It is bounded, so a subsequence  $(c_{n_k})$  weakly converges to some  $c \in X$ . Since  $C$  is convex,  $c \in C$ . Now,

$$d_C(x) \leq d(x, c) \leq \liminf_{n \rightarrow \infty} d(x_n, c) = d_C(x).$$



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# Final remarks

- Projections are nonexpansive even in CAT(1) spaces.
- Our assumptions:  $X$  a CAT(0) space and  $C \subset X$  complete convex.
- Still things to do: e.g., are weakly closed Čebyšev sets convex?

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# Suggestions for our next talks

- Examples (hyperbolic spaces, manifolds, buildings, . . . )
- Connections to Banach space geometry
- Topologies on  $CAT(0)$  spaces
- Alternating projections
- Fixed point theory
- Applications (phylogenetic trees, robotics)

# Euclidean buildings

**Miroslav Bačák**

CARMA, University of Newcastle

13 April 2010



# Contents of the talk

- 1 Simplicial complexes
  - Gluing definition
  - Examples
  - Metrizing definition
- 2 Euclidean buildings
  - Definition
  - Examples
  - Euclidean buildings are  $CAT(0)$
- 3 Final remarks

# Piecewise Euclidean simplicial complex

## Definition

Let  $(S_\lambda)_{\lambda \in \Lambda}$  be a family of simplices  $S_\lambda \subset \mathbb{R}^{n_\lambda}$ . Let  $X = \bigcup_{\lambda \in \Lambda} (S_\lambda \times \{\lambda\})$ . Let  $\sim$  be an equivalence relation and  $K = X / \sim$ . Let  $p : X \rightarrow K$  be the projection and define  $p_\lambda : S_\lambda \rightarrow K$  by  $p_\lambda = p(\cdot, \lambda)$ . Then  $K$  is a *piecewise Euclidean simplicial complex* if

- 1 the map  $p_\lambda$  is injective for every  $\lambda \in \Lambda$ ,
- 2 if  $p_\lambda(S_\lambda) \cap p_{\lambda'}(S_{\lambda'}) \neq \emptyset$ , then there is an isometry  $h_{\lambda, \lambda'}$  from a face  $T_\lambda \subset S_\lambda$  onto a face  $T_{\lambda'} \subset S_{\lambda'}$  such that  $p_\lambda(x) = p_{\lambda'}(x')$  if and only if  $x' = h_{\lambda, \lambda'}(x)$ .

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# Intrinsic metric

$K$  comes equipped with the quotient pseudometric, which coincide with so-called intrinsic pseudo metric.

An  $m$ -string in  $K$  from  $x$  to  $y$  is a sequence

$\sigma = (x_0, \dots, x_m) \subset K$  such that  $x = x_0$ ,  $y = x_m$  and for each  $i = 0, \dots, m-1$ , there is a simplex  $S(i)$  containing  $x_i$  and  $x_{i+1}$ .

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The *intrinsic pseudometric* on  $K$  is defined by

$$d(x, y) = \inf \{ \ell(\sigma) : \sigma \text{ a string from } x \text{ to } y \}.$$

Let  $x \in K$ . For a simplex  $S$  containing  $x$ , define

$$\varepsilon(x, S) = \inf \{ d_S(x, T) : T \text{ a face of } S \text{ and } x \notin T \}$$

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If  $\varepsilon(x) > 0$  for all  $x \in K$ , then  $d$  is a metric and  $(K, d)$  is a length space.

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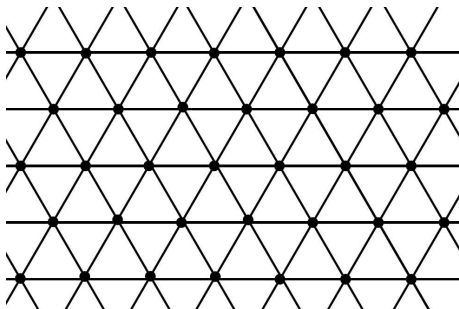
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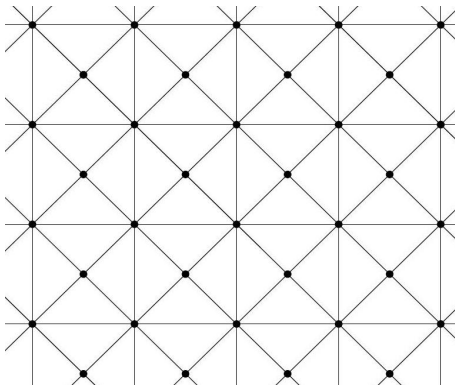
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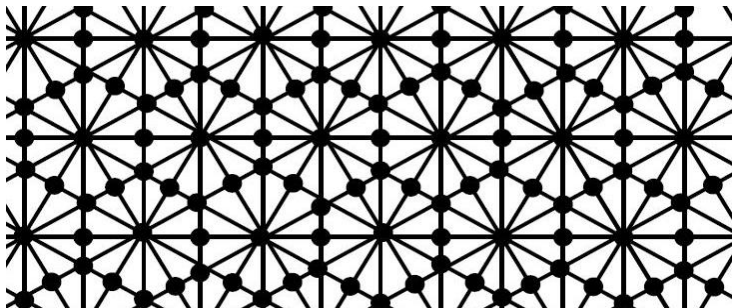
# Examples of simplicial complexes



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# Abstract simplicial complex

## Definition

An *abstract simplicial complex* consists of of a set  $V$  and a collection  $\mathcal{S}$  of (nonempty) finite subsets of  $V$ , such that

- $\{v\} \in \mathcal{S}$  for all  $v \in V$ ,
- if  $S \in \mathcal{S}$ , then any nonempty subset  $T$  of  $S$  belongs to  $\mathcal{S}$ .

We call elements of  $V$  vertices and elements of  $\mathcal{S}$  simplices.

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# Affine realization

Let  $K$  be an abstract simplicial complex with vertex set  $V$ . Let  $W$  be a real vector space with basis  $W$ . The *affine realization*  $|S|$  of a simplex  $S \subset K$  is the convex hull of  $S$  in  $W$ .

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# Metrizing affine realization

Alternative definition of piecewise Euclidean simplicial complex:

## Definition

A piecewise Euclidean simplicial complex consists of:

- an abstract simplicial complex,
- a set  $\text{Shapes}(K)$  of simplices  $S'_i \subset \mathbb{E}^{n_i}$
- for any simplex  $S$  in the affine realization of  $K$ , an affine isomorphism  $f_S : S' \rightarrow S$ , where  $S' \in \text{Shapes}(K)$ . If  $T$  is a face of  $S$ , then  $f_S^{-1} \circ f_T$  is required to be an isometry from  $T'$  onto a face of  $S'$ .

Using piecewise linear path, we define the intrinsic pseudometric.

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# Euclidean building

## Definition

A *Euclidean building* of dimension  $n$  is piecewise Euclidean simplicial complex  $X$  such that

- 1  $X$  is a union of a collection  $\mathcal{A}$  of subcomplexes  $E$ , called *apartments*, such that  $d_E$  makes  $(E, d_E)$  isometric to  $\mathbb{E}^n$  and induces the given Euclidean metric on each simplex.
- 2 Any two simplices  $A, B$  are contained in an apartment.
- 3 Given two apartments  $E, E'$  containing  $A$  and  $B$ , there exists a simplicial isometry from  $(E, d_E)$  onto  $(E', d_{E'})$  which leaves  $A$  and  $B$  fixed.

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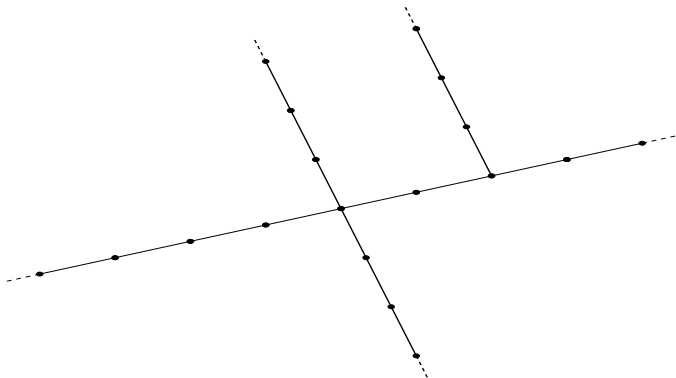
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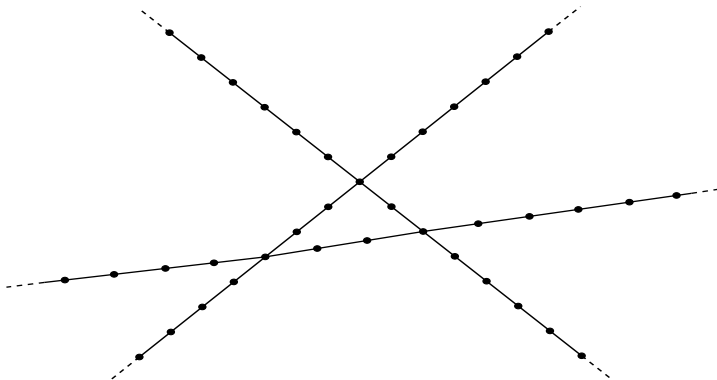
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This is a building:



This is not a building:



# Main theorem

## Theorem

*Let  $X$  be a Euclidean building. Then  $X$  is a complete CAT(0) space.*

Let  $C$  be a chamber in an apartment  $E \subset X$ . Define a retraction  $\rho_{C,E} : X \rightarrow E$  by

$$\rho_{C,E}(x) = \phi_{E,E'}(x)$$

where  $E'$  is an apartment containing both  $x$  and  $C$ , and  $\phi_{E,E'} : E' \rightarrow E$  is the unique isometry between  $E'$  and  $E$ .

Then  $\rho_{C,E} : X \rightarrow E$  is a nonexpansive simplicial retraction.

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Given  $x, y \in X$ , choose an apartment  $E \subset X$  containing them and let  $[x, y]$  be the line segment joining them in  $E$ . Choose  $p = p_t \in [x, y]$ , where  $0 \leq t \leq 1$ , choose  $C \subset E$  be a chamber containing  $p$ , and let  $\rho = \rho_{C,E}$ . Take any  $z \in X$ .

We must verify:

$$d^2(z, p) \leq (1-t)d^2(z, x) + td^2(z, y) - t(1-t)d^2(x, y).$$

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# Final remarks

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- More general definition of buildings: a **non**-simplicial complex.
- Modern definition of buildings:  $W$ -metric spaces.  
This approach does not use apartments.

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# Modern definition of buildings

We start with a Coxeter system  $(W, S)$ , where

- $W$  is a (reflection) group
- $S$  is a set of generators of  $W$ .

A building is a pair  $(\mathcal{C}, \delta)$  where  $\mathcal{C}$  is a nonempty set (of chambers) and a 'distance' function  $\delta : \mathcal{C} \times \mathcal{C} \rightarrow W$  such that

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- 3 If  $\delta(C, D) = w$ , then for any  $s \in S$  there is a chamber  $C' \in \mathcal{C}$  such that  $\delta(C', C) = s$  and  $\delta(C', D) = sw$ .

# Suggestions for our next talks

- Examples (hyperbolic spaces, Riemannian manifolds, . . . )
- Connections to Banach space geometry
- Topologies on  $CAT(0)$  spaces
- Alternating projections
- Fixed point theory
- Groups and  $CAT(0)$  spaces
- Applications (phylogenetic trees, robotics, . . . )

# The weak topology on $CAT(0)$ spaces

**Miroslav Bačák**

CARMA, University of Newcastle

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# Overview

- 1976: Lim defined  $\Delta$ -convergence in metric spaces
- 2004: Sosov defined  $\Phi$ -convergence in metric spaces
- 2008: Kirk and Panyanak used  $\Delta$ -convergence in  $CAT(0)$ , and asked for topology
- 2009: Espínola and Fernández-León modified  $\Phi$ -convergence to get equivalent condition for  $\Delta$ -convergence in  $CAT(0)$
- 2009: (M.B.) definition of a topology that corresponds to the above convergence

# Weak convergence

Let  $(X, d)$  be a metric space. Suppose  $(x_\nu) \subset X$  is a bounded net and define its *asymptotic radius* about a given point  $x \in X$  as

$$r(x_\nu, x) = \limsup_{\nu} d(x_\nu, x),$$

and the *asymptotic radius* as

$$r(x_\nu) = \inf_{x \in X} r(x_\nu, x).$$

Further, we say that a point  $x \in X$  is the *asymptotic center* of  $(x_\nu)$  if

$$r(x_\nu, x) = r(x_\nu).$$

Recall that the asymptotic center of  $(x_\nu)$  exists and is unique, if  $X$  is a complete CAT(0) space.

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# Weak convergence

## Definition (Lim)

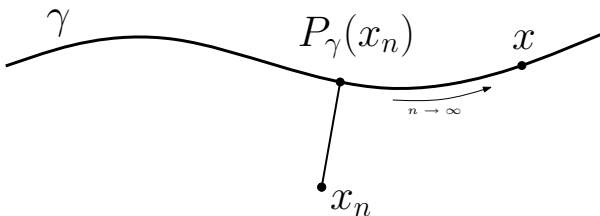
We shall say that  $(x_\nu) \subset X$  *weakly converges* to a point  $x \in X$  if  $x$  is the asymptotic center of each subnet of  $(x_\nu)$ . We use the notation  $x_\nu \xrightarrow{w} x$ .

Clearly, if  $x_\nu \rightarrow x$ , then  $x_\nu \xrightarrow{w} x$ .

# Weak convergence

## Proposition (Espínola, Fernández-León)

Let  $(X, d)$  be a complete  $CAT(0)$  space,  $(x_n) \subset X$  be a bounded sequence and  $x \in X$ . Then  $x_n \xrightarrow{w} x$  if and only if, for any geodesic  $\gamma$  through  $x$  we have  $d(x, P_\gamma(x_n)) \rightarrow 0$ .



# Weak topology

## Definition (M.B. 2009)

Let  $X$  be a complete CAT(0) space. A set  $M \subset X$  is *open* if, for any  $x_0 \in M$ , there are  $\varepsilon > 0$  and a finite family of nontrivial geodesics  $\gamma_1, \dots, \gamma_N$  through  $x_0$  such that

$$U_{x_0}(\varepsilon, \gamma_1, \dots, \gamma_N) = \{x \in X : d(x_0, P_{\gamma_i}(x)) < \varepsilon, i = 1, \dots, N\}$$

is contained in  $M$ . Denote  $\tau$  the collection of all open sets of  $X$ .

The sets  $U_{x_0}(\varepsilon, \gamma_1, \dots, \gamma_N)$  are convex iff  $X$  has the property (N).



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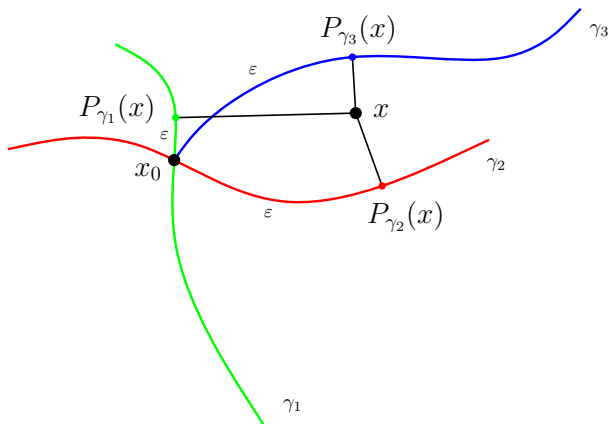
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# Weak topology

$$U_{x_0}(\varepsilon, \gamma_1, \gamma_2, \gamma_3)$$



# Weak topology

## Theorem (M.B. 2009)

Let  $(X, d)$  be a complete CAT(0) space and  $\tau$  as above. Then

- 1  $\tau$  is a Hausdorff topology on  $X$ ,
- 2  $x_\nu \xrightarrow{\tau} x$  if and only if  $x_\nu \xrightarrow{w} x$ , for  $(x_\nu) \subset X$  a bounded net and  $x \in X$ .
- 3  $\tau$  is weaker than the topology induced by the metric  $d$ ,
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# Properties of the weak topology

The weak topology in Banach spaces:

compactness = sequential compactness = countable compactness

But not in CAT(0) spaces!

## Example

Consider a countable set  $\{x_1, x_2, \dots, x_\infty\}$ , and for every  $n \in \mathbb{N}$ , join  $x_\infty$  with  $x_n$  by a geodesic of length  $n$ . Then  $x_n \xrightarrow{w} x_\infty$ , but is unbounded.  $X$  is sequentially  $w$ -compact, but not (countably)  $w$ -compact.

Let  $C$  be a *convex* set in a complete CAT(0) space. Then  $\overline{C} = \overline{C}^w$ .



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# Open problems

Let  $(X, d)$  be a complete CAT(0) space.

- Let  $(x_n) \subset X$  be a bounded sequence weakly converging to a point  $x \in X$ . Is then the case that

$$\{x\} = \bigcap_{n \in \mathbb{N}} \overline{\text{co}} \{x_n, x_{n+1}, \dots\}?$$

Note: “ $\subset$ ” is known. The converse is true if we assume the property (N).

- Suppose  $C \subset X$  is compact. Is  $\overline{\text{co}} C$  compact?
- Is the weak topology restricted on balls metrizable?